

COMISEF WORKING PAPERS SERIES

WPS-002 09/09/2008

Determination of sequential best replies in n-player games by Genetic Algorithms

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Determination of sequential best replies in n-player games by Genetic Algorithms

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Abstract

An iterative algorithm for establishing the Nash Equilibrium in pure strategies (NE) is proposed and tested in Cournot Game models. The algorithm is based on the convergence of sequential best responses and the utilization of a genetic algorithm for determining each player's best response to a given strategy profile of its opponents. An extra outer loop is used, to address the problem of finite accuracy, which is inherent in genetic algorithms, since the set of feasible values in such an algorithm is finite. The algorithm is tested in five Cournot models, three of which have convergent best replies sequence, one with divergent sequential best replies and one with "local NE traps" (Son and Baldick 2004), where classical local search algorithms fail to identify the Nash Equilibrium. After a series of simulations, we conclude that the algorithm proposed converges to the Nash Equilibrium, with any level of accuracy needed, in all but the case where the sequential best replies process diverges.

Keywords: Genetic Algorithms, Cournot oligopoly, Best Response, Nash Equilibrium

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¹Financial support from the EU Commission through MRTN-CT-2006-034270 COMISEF is gratefully acknowledged.

1 Introduction

We utilize a genetic algorithm to determine a player's best reply in a sequential best reply process context, that converges to a Nash Equilibrium in pure strategies, in Cournot oligopoly games (Cournot 1838). Lemke and Howson (1964) discovered the LCP algorithm that allows for the derivation of the Nash Equilibrium in pure strategies (NE) in a two-player game, but unfortunately, that algorithm cannot be applied in n-player games. Therefore, computational methods are needed in order to calculate the NE's of a n-player game, when an analytical calculation is not possible. Two major categories of this kind of algorithms are evolutionary methods (see for example Vriend 2000, or Protopapas and Kosmatopoulos 2008), which use adaptive agents that represent players, who "learn" using a learning algorithm, and iterative algorithms, which are based on the convergence of the best-reply sequence to a NE, in specific classes of games (see for example Weber and Overbye 1999 or Hobbs et al. 2000).

The algorithm we introduce is an "iterative Nash Equilibrium Search Algorithm" (Son and Baldick 2004). These algorithms are based on the convergence of the "best reply process" (Fudenberg and Tirole 1991) to the Nash Equilibrium in pure strategies (NE). Cournot (1838) already proposed an adjustment process for the two-player case, where players decide their quantities sequentially, and each player's decision is the best response to the other player's total output, as it has been formed at the previous round. It's easy to generalize to the n-player case, and the process of the sequential best replies can converge to the NE, under certain provisions (Milgrom and Roberts 1990, Kukushin 1994, Voorneveld 2000, Dubey et al. 2006). In the case of convergence to a NE, we then say that the NE is "asymptotically stable" (Fudenberg and Tirole 1991).

In the cases in which the best-reply process converges to a NE an iterative algorithm can be used to discover an unknown NE. An optimization algorithm can be used to determine the first player's reply to an initial strategy profile of his opponents. Then that reply is used as the player's strategy in the strategies profile on the next iteration, when the next player's reply will be defined by the optimization algorithm, and so on. That loop ends when the NE has been encountered or a given termination condition holds. These algorithms are known as "iterative NE search algorithms" (Son and Baldick 2004). The conceptual model of an "iterative NE search algorithm", as given in that article is as follows: First a random strategy is picked as the initial strategy for each player. Then, the profit maximization problem with other players' choices taken as given, is solved for each player and its strategy is updated accordingly. This step is executed for each player in turn, until the NE (as described by an appropriate condition) is found, or another termination condition is met.

Two kinds of problems can arise: the first one arises when the maximum number of iterations is not high enough to determine the NE accurately. A similar cause could be that one of the NE quantities is an irrational number and therefore cannot be discovered with infinite accuracy. This kind of problem cannot be solved in the general case. The only feasible thing to do is to increase the number of iterations, to achieve better accuracy. The second kind of problem

is much more serious. As Son and Baldick (2004) point out, when a classical local search algorithm -such as Newton’s method- is used for the discovery of a player’s optimal response (see for example in Hobbs et al. 2000), the best-reply sequence can converge to a “local NE trap” (Son and Baldick 2004), i.e. a strategy profile in which each player’s strategy is a local optimum in its optimization problem, but not a global one, and therefore it’s not a NE. We use a genetic algorithm as the optimization algorithm in the best-reply determination problem, in order to avoid these “local NE traps”. However, since the chromosomes’ values belong in a finite set, in any genetic algorithm, an external loop should be utilized to increase the solution’s accuracy, and consequently address the problem of the first kind, described earlier, as well.

2 The Algorithm

Since we deal with Cournot oligopoly models (Cournot 1838) the player’s strategic choices have to do with quantities of a single, homogeneous product, that are either real or discrete¹. The values of the chromosomes of the GA employed can therefore represent real numbers². Since a chromosome’s value is an integer (binary) number, a usual decoding scheme is employed (Vriend 2000), adjusted to allow for positive minimum values for the chromosomes.

$$q = q_{min} + \frac{q_{max} - q_{min}}{2^l - 1} \cdot \sum_{n=1}^l b_n 2^{n-1} \quad (1)$$

where b_n is the n^{th} bit of the chromosome, and l is the total number of bits in the chromosome. Adjusted this way, the decoding formula implies that a quantity has a minimum value of q_{min} , a maximum q_{max} and a finite set of values in between, all with equal probabilities.

The algorithm we introduce is as follows:

1. Pick minimum and maximum values for the chromosome values (and consequently, the quantity choice) of each player.
2. Pick n random initial quantities for the n players, creating an initial profile of strategies.
3. For each player, solve its profit maximization problem, using a “canonical Genetic Algorithm” (Goldberg 1988).
4. Update the corresponding player’s strategy in the profile of active strategies.
5. Loop steps 3-4 for the next player, until all players’ strategies have been determined.
6. Loop to step 3, unless the profile of active strategies has remained unaltered (so NE is assumed to be found) or a given number of maximum iterations has been reached.

¹In the original Cournot’s model, quantities are continuous.

²If the non-continuous version of the Cournot Game is addressed, a ‘1-1’ correspondence between chromosome values and allowed quantities can be utilized to simplify the algorithm.

7. If NE is assumed to be found, terminate.
8. If the accuracy of the current solution is considered to be adequate, terminate. Else update the minimum and maximum values of the players' chromosomes, to allow a better refinement of the solution space and repeat from step 1.

The “canonical GA” is a single-population genetic algorithm with the probability for a chromosome to be selected as a parent being proportional to its fitness (roulette wheel selection), single-point crossover with fixed probability of application, fixed mutation probability throughout the GA process and no elitism, i.e. the next generation is consisted entirely of the offspring of the current chromosome population (Goldberg 1988). We also use “ordered” fitness in our implementation (chromosomes are ranked on the basis of their implied profits and fitness values ranging from 1 to the number of the chromosomes in the population, are attributed to them).

Since the strategy of a player is updated in the active strategies profile each time its profit maximization problem is addressed, we have a “sequential best-reply correspondence” (Dubey et al. 2006), where each player determines its strategy and the next player considers as given that updated strategy, so “responds” in a sense, to that choice. It is possible to adjust the algorithm to function with “simultaneous best replies” (Dubey et al. 2006), or with different opponents' quantities to be considered as given from the active player, when its profit maximization problem is addressed³. In any case, the “sequential best reply correspondence” converges to a NE under a broader set of assumptions in the Cournot case or in any game with strategic substitutes in general (Amir 1996, Dubey et al. 2006).

The convergence of the best-replies sequence to the NE, also means that the accuracy of the algorithm is better for a larger number of iterations in the internal loop (steps 3-5), i.e. the values of the quantities in the sequence will be closer to the NE values. Therefore, one can use the minimum and maximum values attained for any players' quantity in the current internal iteration, as the minimum and maximum allowable values for the chromosomes in the outer loop (steps 1-7). In practice a qualitatively assessment of the situation can provide better results with a smaller number of external iterations, and that's the tactic we employ.

3 The Models

A linear Cournot model introduced by Alkemade et al. (2007) is used as an initial testbed. The polynomial and exponential models used in Protopapas and Kosmatopoulos (2008) are also used, adjusted in the cost functions. The new cost functions are not the same for all players, allowing the study of non-

³Fundenberg and Tirole (1981) for example present the case when the expected quantity chosen by any other player is a weighted average of the quantities chosen in the past from that player

symmetric Cournot games. The inverse demand in the first model is given by

$$P = 256 - Q \tag{2}$$

with $Q = \sum_{i=1}^n q_i$, while cost functions are the same for the n players:

$$c(q_i) = 56q_i \tag{3}$$

The polynomial Cournot model introduced in Protopapas and Kosmatopoulos (2008) has inverse demand function:

$$P = aQ^3 - b \tag{4}$$

where $a = -1$ and $b = 7.3710^7$ and the same common cost functions, as in the previous model. In the exponential model the inverse demand function is (Protopapas and Kosmatopoulos 2008)

$$P = aQ^{3/2} - b \tag{5}$$

a, b being equal to the previous case. In this implementation of the two models we assume different cost function for each player:

$$c_k = kxq_i + y \tag{6}$$

where k is the index of the respective player, $x = 10$ and $y = 10$, addressing the case of non-symmetric Cournot games. In all three models we study the $n = 4$ player case. We used MATLAB Optimization Toolbox to discover the unique NE in the polynomial and exponential models (table 1). For the linear model, NE is derived easily and it is $q^N = 40$ for each one of the 4 players .

Player	Polynomial	Exponential
1	86.9400905	86.75703497
2	86.94006293	83.05809161
3	86.94003537	79.35914826
4	86.94000781	75.66020491

Table 1: NE in Polynomial and Exponential Models

In all these models, the assumptions that, as proved in Dubey et al (2006), guarantee the convergence of the sequential best reply process to a NE, hold and, furthermore, the NE is unique (as it can be easily proven using elementary calculus), and no local optima (“local NE traps”) exist.

A model introduced by Arifovic (1994) is used for the $n = 2$ case, with parameters chosen in a way such that a) a NE exists and b) the best-reply sequence diverges from that NE. A sufficient condition for the latter (Fundenberg and Tirole 1991) is

$$\frac{\partial^2 u_1}{\partial q_1 \partial q_2} \frac{\partial^2 u_2}{\partial q_1 \partial q_2} > \frac{\partial^2 u_1}{\partial^2 q_1^2} \frac{\partial^2 u_2}{\partial^2 q_2^2} \tag{7}$$

where u_1, u_2 are the payoff functions for each player, which are functions of the chosen quantities q_1, q_2 . The inverse demand function in Arifovic's (1994) model are

$$P = A - B(q_1 + q_2)$$

and each player's cost is given by

$$c = xq_i + yq_i^2$$

The payoff functions are, therefore

$$u_i = Pq_i - c_i = [A - B(q_i + q_j)]q_i - xq_i - yq_i^2$$

where $q_i = \{1, 2\}$ and $q_j = \{2, 1\}$. So,

$$\frac{\partial u_i}{\partial q_i} = A - B(q_i + q_j) - Bq_i - x - 2yq_i$$

and

$$\frac{\partial u_i}{q_i} = 0 \Leftrightarrow q_i = \frac{A - x - Bq_j}{2B + 2y}$$

From the latter, we derive the "reaction functions" that determine player i's best response to a given quantity choise by player j,

$$r_i(q_j) = \frac{A - x - Bq_j}{2B + 2y} \quad (8)$$

and the Nash Equilibrium quantities

$$q_i^N = \frac{A - x}{3B + 2y} \quad (9)$$

Since a maximum is required, the second order partial derivatives of the payoff functions must be negative at the NE quantities

$$\frac{\partial^2 u_i}{\partial^2 q_i} < 0 \Leftrightarrow B + y > 0$$

and from (7)

$$\frac{\partial^2 u_1}{\partial q_1 \partial q_2} \frac{\partial^2 u_2}{\partial q_1 \partial q_2} > \frac{\partial^2 u_1}{\partial^2 q_1^2} \frac{\partial^2 u_2}{\partial^2 q_2^2} \Leftrightarrow B^2 > 4(B + y)^2$$

Since $B + y > 0$ we have

$$B^2 > 4(B + y)^2 \Leftrightarrow y < \frac{-B}{2}$$

an finally,

$$-B < y < \frac{-B}{2} \quad (10)$$

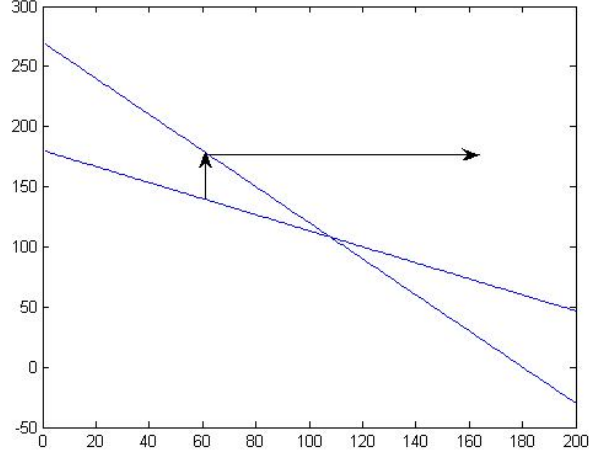


Figure 1: Best replies in Arifovic's model

For these values of y there is a NE and the best replies sequence diverges from it, at the same time. For the values $A = 1000, B = 5, x = 100$ and $y = \frac{-10}{3}$ used for simulations, the best reply sequence diverges (see fig. 1).

Finally, we use one of the “quasi-Cournot” models used in Son and Baldick (2004). Although the models employed there are not Cournot Games per se, since the players have different demand functions, existence of “local NE traps” makes them quite interesting to study. As Son and Baldick (2004) prove, a “local search algorithm” can get stuck to a “local NE trap” instead of finding the absolute NE. The model we use (introduced by Son and Baldick 2004) is a duopoly. The two players' payoff functions are

$$u_1(q_1, q_2) = 21 + q_1 \sin \pi q_1 + q_1 q_2 \sin \pi q_2$$

$$u_2(q_1, q_2) = 21 + q_2 \sin \pi q_2 + q_1 q_2 \sin \pi q_1$$

and, as reported in Son and Baldick (2004) the NE quantities are⁴ $(q_1, q_2) = (6.61, 6.61)$ and the “local NE traps” where the local search algorithms (Weber and Overbye 1999, Hobbs et al. 2000) could erroneously converge to are $(6.58, 4.66)$, $(0.25, 0.92)$ and $(6.54, 2.8)$.

⁴We discovered, after analyzing the model, that these values are approximations of the respective quantities, to the second decimal digit.

4 Results

4.1 Linear Model

For minimum quantity $Q_{min} = 0$, maximum quantity $Q_{max} = 120$ for all players, population size $pop = 100$ chromosomes, probability for crossover $p_c = 1$ and probability of mutation of a bit $p_m = 0.01$ we got the following results (table 2⁵).

88.554	53.287	40.964	38.243	38.555	39.274	39.747	39.945	40.02	40.026
47.109	50.2	45.586	41.915	40.313	39.844	39.795	39.869	39.946	39.987
28.269	39.233	42.405	42.16	41.146	40.444	40.12	39.995	39.969	39.977
18.047	28.64	35.522	38.841	39.993	40.219	40.195	40.095	40.032	40.005
40.015	40.005	40.001	40	39.999	40	40	40	40	40
40.001	40.004	40.003	40.001	40	40	40	40	40	40
39.989	39.997	40	40	40	40	40	40	40	40
39.997	39.997	39.998	39.999	40	40	40	40	40	40

Table 2: Linear Model

The algorithm converged to the NE, after the 16th iteration. Allowing the algorithm to continue until the 1000th iteration, we had⁶ expected frequency of the state defined by the NE strategy (all players choose $Q_i = 40$) $\hat{\pi}_N = 0.984$ and expected return time to this state $\hat{m}_{NN} = 1.01626$.

4.2 Polynomial Model

Using the same parameter set as in the linear case, we observe the process does not converge to a NE (for 1000 iterations of the inner loop) with an adequate level of accuracy. Chosen quantities (after an “initial” number of 100 iterations have passed) range between 86 and 87.5 (see fig. 2).

A second outer loop iteration is utilized with $Q_{min} = 86$ and $Q_{max} = 87.5$ for all 4 players. The quantities chosen by each player, for iterations 100, ..., 1000, range between the values seen on table 3:

	player 1	player 2	player 3	player 4
min	86.93750	86.93750	86.93750	86.93750
max	86.94310	86.94400	86.94460	86.94370

Table 3: Polynomial Model. Second outer loop

Setting the minimum and maximum allowable quantities for the players equal to those values acquired on table 3 and executing another iteration of

⁵Each line represents the respective player’s quantity at the given round. Iterations 1-10 are in the first block and iterations 11-20 in the second

⁶The random process underlying a “canonical” Genetic Algorithm is an ergodic Markov chain, and the same holds, consequently, for the random process defined by the strategies chosen.

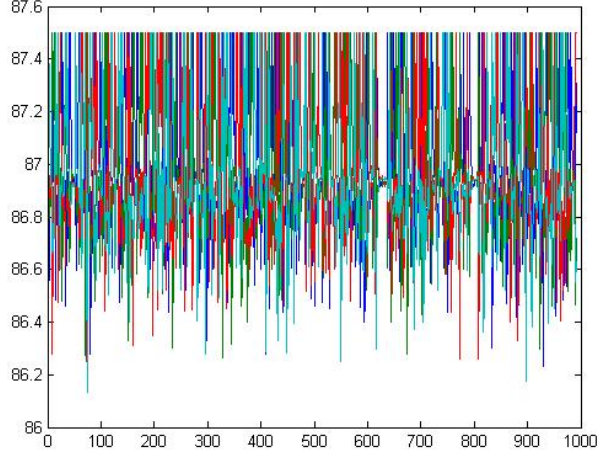


Figure 2: Polynomial model. First outer loop.

the outer loop, we got the maximum and minimum quantities in the iterations 100, ..., 1000 of the inner loop shown on table 4 and fig. 3.

	min	max	mean
player 1	86.940046425672900	86.940162502539200	86.940091341955200
player 2	86.940012996781300	86.940162502539200	86.940061909895200
player 3	86.939973528073800	86.940162502539200	86.940037999838900
player 4	86.939924654316600	86.940019043368400	86.940006131756100

Table 4: Polynomial Model. Third outer loop

We could continue this process of refining the minimum and maximum quantities and executing more iterations of the outer loop of the algorithm, if better accuracy was required.

4.3 Exponential Model

For $pop = 100$, $p_c = 1$, $p_m = 0.01$, and initial $Q_{min} = 0$, $Q_{max} = 120$ we have the results shown on table 5 and fig. 4:

Repeating the outer loop for minimum and maximum allowable values, according to table 5 we had the results shown on table 6, and fig. 5.

Finally, we executed a third iteration of the outer loop, setting the minimum and maximum allowable values equal to those of table 6. The results are shown on table 7.

A comparison between the minimum and maximum values of the players, attained in the third iteration of the outer loop leads to the conclusion (also

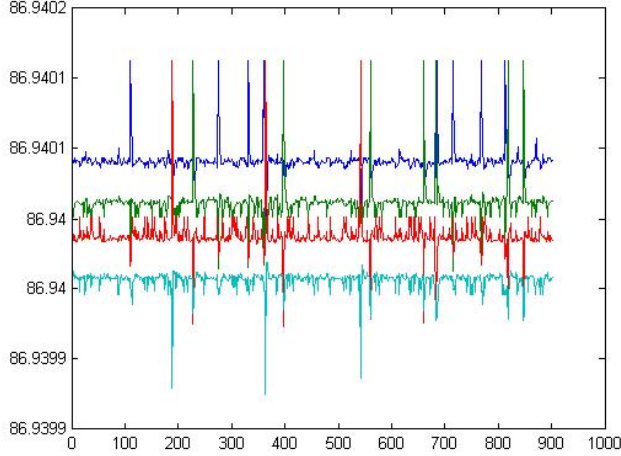


Figure 3: Polynomial model. Third outer loop.

	min	max	mean
player 1	86.620985623346000	87.880599861717100	86.871269377449000
player 2	81.249886751066900	83.759387740505000	83.039159084961000
player 3	74.999880790596800	79.931716853825400	79.361882675560900
player 4	74.999880790596800	77.953794435305100	75.557777410666100

Table 5: Exponential model. First outer loop.

seen by comparing tables 7 and 1) that the algorithm gives the NE quantities with an accuracy of 4 decimal digits.

4.4 Model with divergent best replies

We used various parameter sets for the simulations in the divergent model, inspired by Arifovic(1994). In all cases, the algorithm diverges. In fig. 6 we see the outcome for $Q_{min} = 0$ and $Q_{max} = 300$, for both players.

Since the best response to $q_i = 0$ is $q_j = 270$ and to $q_j = 270$ it is $q_i = -135 < 0$ (as derived from eq.(8)), the situation depicted in fig. 6 is easily understood.

4.5 Model with local NE traps

We used the parameters $pop = 100$, $p_c = 1$, $p_m = 0.01$, and $Q_{min} = 0$, $Q_{max} = 7.5$ for each of the two players. We run 100 simulations⁷, starting from different

⁷Just one iteration of the outer loop. The minimum and maximum quantities were not updated

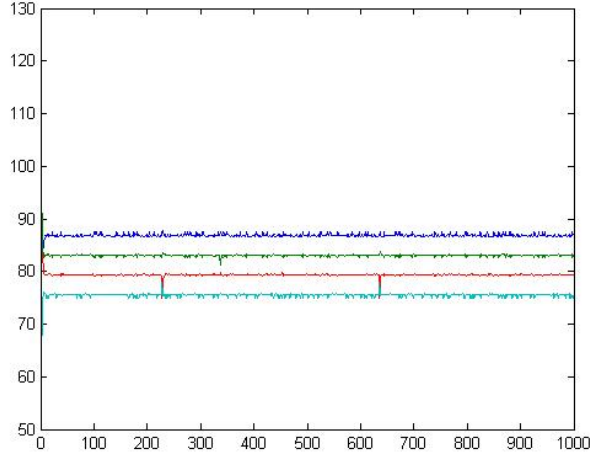


Figure 4: Exponential model. First outer loop.

	min	max	mean
player 1	86.718436392246600	86.777500150203800	86.757826134771000
player 2	83.037370488520100	83.066017366425900	83.057558000397000
player 3	79.321249409913400	79.363343823760800	79.357501005526800
player 4	75.639685287175500	75.732500708103900	75.661182399135300

Table 6: Exponential model. Second outer loop.

quantities in the initial strategy profile, and the algorithm always converged to the NE quantities (within a given degree of accuracy of course). So the local NE traps were avoided in all of the 100 runs of the simulation conducted. On table 8 we see the first 10 iterations of the inner loop for two of those runs.

5 Discussion

The algorithm introduced here is quite effective when the theoretical optimal response sequence converges to the NE. The algorithm converged to the NE⁸, in all of the models studied here, in which this precondition holds. The “linear”, “polynomial” and “exponential” models are games with “strategic substitutes” (Bulow et al. 1985), and consequently sequential best replies converge to the NE (Amir 1996, Dubey et al. 2004). Another trivial necessary condition is that the NE quantities belong to the feasible set of the chromosome values. This is not always possible, since the NE quantities might sometimes be irrational or have a large number of decimal digits, while a typical encoding scheme as

⁸within a finite level of accuracy

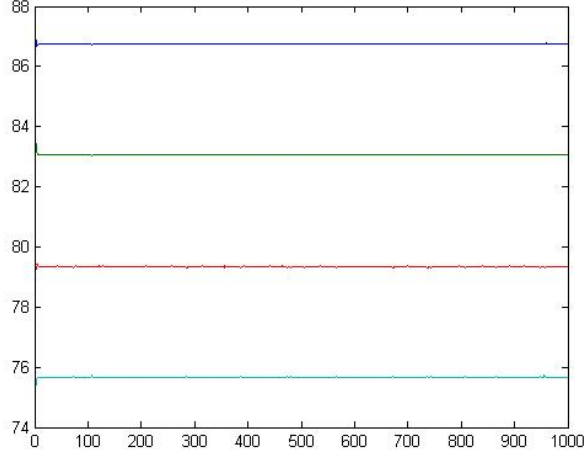


Figure 5: Exponential model. Second outer loop.

	min	max	mean
player 1	86.755675667069100	86.757312379383400	86.757064178033700
player 2	83.057409410926800	83.058247337057300	83.058084838326400
player 3	79.358082017011800	79.359397508843500	79.359154305916900
player 4	75.659988591350600	75.662889164536500	75.660173659449200

Table 7: Exponential model. Third outer loop.

the one used, implies the chromosomes encode values with finite number of digits. In those cases the outer loop we employed leads to increased accuracy of the computed NE. Those are the cases of the “polynomial” and “exponential” models, where increased accuracy is achieved, after the fine-tuning process of the chromosome values bounds, and the consequent outer loop iterations. Of course, if the Cournot game studied is of the “discrete type” (players can only use discrete quantities), that problem does not exist, provided that the chromosomes have enough digits to hold all the possible admissible quantity values.

The above remarks also hold in the model with “local NE traps”. As pointed earlier, the quantities of the NE and the local NE traps are given with a finite accuracy of two decimal digits by Son and Baldick (2004). The algorithm attains that level of accuracy relatively easily (with $Q_{min} = 0$, $Q_{max} = 7.5$ less than 10 iterations of the inner loop are generally needed to set correctly the three first digits of the players’ quantities). If better accuracy is required more outer loop iterations can be employed.

The only case when the algorithm clearly diverges, is the case of the model with divergent best replies process used. By using $Q_{min} = 0$ and $Q_{max} =$

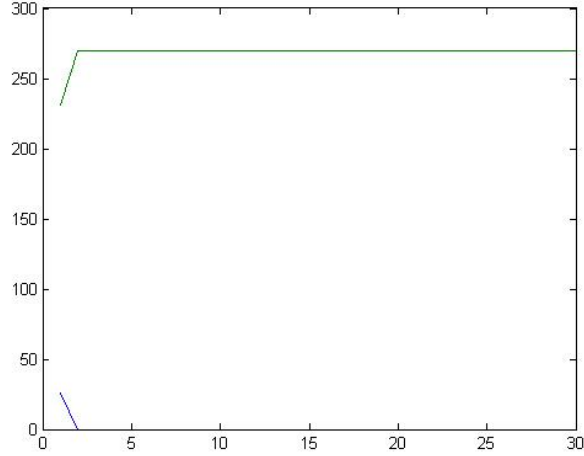


Figure 6: Divergent model.

300⁹, the quantities proposed by the algorithm diverge quickly after the initial iterations of the inner loop, something that leads to a situation where one of the players “picks” the zero quantity. Since the best reply to this quantity is 270, which is correctly identified by the algorithm, and the other player assumes that choice, the best reply of his opponent is then an inadmissible negative quantity. The best reply under the constraint $Q_{min} = 0$ is again zero, so the algorithm attributes this value to the other player correctly, thus entering an infinite path of attributing 0 to one of the players and 270 to the other, ad infinitum.

6 Conclusions

The potency of the genetic algorithm meta-heuristic is evident in the case of Cournot games, as in most other cases genetic algorithms have been applied. The convergence of the sequential best reply search is almost ensured when a genetic algorithm is used for the search of a player’s best response to other players strategies, provided that the theoretical best reply sequence converges to a Nash Equilibrium. This depends on the model, so if appropriate conditions hold for the demand and cost functions, such that the sequence of iterative best replies can be proved to an existing Nash equilibrium then the algorithm should derive that strategy profile. One can also study the case of simultaneous best replies, or a case in which the expected opponents’ quantities are different of those selected by the players at the previous round.

We’ve also seen that even if there are “local NE traps“, a case in which classical local search algorithms fail, a genetic algorithm will converge to the

⁹and random initial quantities as always

iter	player 1	player 2	player 1	player 2
1	0	6.514891639	6.581954081	6.613768686
2	6.617437952	6.611243831	6.611615764	6.611830341
3	6.611866104	6.611801731	6.611808883	6.611808883
4	6.611808883	6.621100064	6.611808883	6.611808883
5	6.610857592	6.611901867	6.611944782	6.611794578
6	6.611801731	6.611808883	6.611944782	6.621100064
7	6.611944782	6.611794578	6.610857592	6.611901867
8	6.611944782	6.611801731	6.562499106	6.621100064
9	6.,611944782	6.611944782	6.61085044	6.611901867
10	6.611794578	6.611808883	6.611801731	6.611808883

Table 8: Local NE traps model. Initial iterations for 2 runs

“true NE“. The only case when the GA did not find the Nash Equilibrium profile is the case when the sequence of best replies diverges. In that case, the quantities proposed by the algorithm also diverge. Finally, the drawback of the accuracy of the genetic algorithm, a usual case in continuous problems, is addressed by introducing an outer loop in which the values sets of the chromosomes are adjusted to improve the accuracy of the calculated NE, after each iteration.

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